# Markov Chains, Mixing Times, and Couplings 

James Marshall Reber<br>Department of Mathematics, Purdue University

September 22, 2018

## PURDUE

## Motivation

## Motivating Question

Preforming a random walk on some graph structure, how long does it take until you are "sufficiently random?"

## Theorem (Diaconis, Bayer '92)

If you riffle shuffle a deck of size $n$, it takes approximately $\frac{3}{2} \log _{2}(n)$ shuffles until the deck is "sufficiently random."

## Graph Theory

## Graph

We define a graph to be a tuple $G=(V, E)$ such that $V$ is a collection of objects called vertices and $E \subseteq V \times V$ is a collection of pairs called edges.

## Example

$V=\{1,2,3\}, E=\{(1,2),(2,3)\}$.


## Graph Theory

## Degree

We define the degree of a vertex to be the number of neighbors, or vertices which are connected by an edge, the vertex has. This is generally denoted by $\operatorname{deg}(x)$.

## Regular

A graph is said to be $n$-regular if the degree of all the vertices is $n$.

## Graph Theory

## Example

$V=\{1,2,3\}, E=\{(1,2),(2,3)\}$.


We see $\operatorname{deg}(2)=2, \operatorname{deg}(1)=1$, and $\operatorname{deg}(3)=1$. This is therefore not regular.

## Graph Theory

## Example

$V=\{1,2,3\}, E=\{(1,2),(1,3),(2,3)\}$.


We see $\operatorname{deg}(2)=2, \operatorname{deg}(1)=2$, and $\operatorname{deg}(3)=2$. This is therefore 2-regular.

## Markov Chains

## Markov Property and Markov Chain

A Markov Chain is a series of random variables $\left(X_{0}, X_{1}, \ldots\right)$ on a common state space $\Omega$ satisfying the Markov Property:

$$
\mathbf{P}\left\{X_{n}=x_{n} \mid X_{1}=x_{1}, \ldots, X_{n-1}=x_{n-1}\right\}=\mathbf{P}\left\{X_{n}=x_{n} \mid X_{n-1}=x_{n-1}\right\} .
$$

## Transition Matrix

We can model Markov Chains using a transition matrix, which is a matrix with entries

$$
P(x, y)=\mathbf{P}\left\{X_{n}=y \mid X_{n-1}=x\right\}
$$

## Markov Chains

## Example Graph



## Example Markov Chain

This Markov chain has transition matrix

$$
P=\begin{aligned}
& 0 \\
& 1
\end{aligned}\left[\begin{array}{cc}
0 & 1 \\
0.1 & 0.9 \\
0.75 & 0.25
\end{array}\right]
$$

## Markov Chains

## Aperiodic and Irreducible

We say our Markov Chain is irreducible if there exists a $t>0$ for all $x, y \in \Omega$ such that

$$
P^{t}(x, y)>0 .
$$

We say that our Markov Chain is aperiodic if

$$
\operatorname{gcd}\left\{t \geq 1 \mid P^{t}(x, x)>0\right\}=1
$$

for all $x \in \Omega$.

## Markov Chains

## Stationary Distribution

If our Markov chain is irreducible, then we have that there exists a unique distribution $\pi$ such that

$$
\pi P=\pi
$$

We call such a distribution a stationary distribution.

## Limiting Distribution

We call a distribution $\hat{\pi}$ a limiting distribution if

$$
\lim _{t \rightarrow \infty} P^{t}(x, y)=\hat{\pi}(y)
$$

If our distribution is aperiodic and irreducible, then we have that the stationary distribution $\pi$ is the limiting distribution $\hat{\pi}$.

## Markov Chains

## Example Graph



## Example Stationary Distribution

Notice that this is aperiodic and irreducible, and so we have a stationary distribution. The stationary distribution is

$$
\pi=\left[\begin{array}{ll}
\frac{5}{11} & \frac{6}{11}
\end{array}\right]
$$

## Markov Chains

## Simple Random Walk

Given some graph $G$, we can define a simple random walk on $G$ to be a Markov chain with state space $V$ and transition matrix

$$
P(x, y)=\left\{\begin{array}{l}
\frac{1}{\operatorname{deg}(x)} \text { if } \mathrm{x} \text { and } \mathrm{y} \text { are neighbors }, \\
0 \text { otherwise }
\end{array}\right.
$$

## Lazy Random Walk

Given some graph $G$, we can define a lazy random walk on $G$ to be a Markov chain with state space $V$ and transition matrix

$$
P(x, y)=\left\{\begin{array}{l}
\frac{1}{2} \text { if } x=y \\
\frac{1}{2 \operatorname{deg}(x)} \text { if } \mathrm{x} \text { and } \mathrm{y} \text { are neighbors, } \\
0 \text { otherwise. }
\end{array}\right.
$$

## Mixing Times

## Total Variation Distance

We define the total variation distance of two probability distributions $\mu$ and $\nu$ on a common state space $\Omega$ to be

$$
\|\mu-\nu\|_{T V}=\max _{A \subseteq \Omega}|\mu(A)-\nu(A)|
$$

In particular, we care about

$$
d(t):=\left\|P^{t}(x, \cdot)-\pi(\cdot)\right\|_{T V}
$$

## Mixing Time

We define the mixing time of a Markov chain to be

$$
t_{\operatorname{mix}}(\epsilon):=\min \{t \mid d(t) \leq \epsilon\}
$$

## Coupling

## Markovian Coupling of Markov Chains

We define a Markovian coupling of two Markov chains $\left(X_{t}\right)$ and $\left(Y_{t}\right)$ with common state space $\Omega$ and transition matrix $P$ to be the process $\left(X_{t}, Y_{t}\right)_{t=0}^{\infty}$ over $\Omega \times \Omega$, with the addendum that

$$
\mathbf{P}\left\{X_{t+1}=x^{\prime} \mid X_{t}=x, Y_{t}=y\right\}=P\left(x, x^{\prime}\right)
$$

and

$$
\mathbf{P}\left\{Y_{t+1}=y^{\prime} \mid X_{t}=x, Y_{t}=y\right\}=P\left(y, y^{\prime}\right)
$$

We will also require that $X_{s}=Y_{s}$ for some $s$ implies $X_{t}=Y_{t}$ for all $t \geq s$. A coupling is not a required to be Markovian (and it may not even be the optimal coupling), but in general we want our Markov chains to be Markovian.

## Coupling

## Theorem

Let

$$
\tau:=\min \left\{t \mid X_{s}=Y_{s} \text { for all } s \geq t\right\}
$$

Then we have

$$
\begin{gathered}
d(t) \leq \max _{x, y \in \Omega}\left\|P^{t}(x, \cdot)-P^{t}(y, \cdot)\right\|_{T V} \\
\leq \max _{x, y \in \Omega} \mathbf{P}\left\{\tau>t \mid X_{0}=x, Y_{0}=y\right\} \\
\leq \max _{x, y \in \Omega} \frac{\mathbf{E}\left(\tau \mid X_{0}=x, Y_{0}=y\right)}{t}
\end{gathered}
$$

## Coupling

## Theorem

Let

$$
\tau:=\min \left\{t \mid X_{s}=Y_{s} \text { for all } s \geq t\right\}
$$

Then we have

$$
\begin{aligned}
& d(t) \leq \max _{x, y \in \Omega}\left\|P^{t}(x, \cdot)-P^{t}(y, \cdot)\right\|_{T V} \\
& \leq \max _{x, y \in \Omega} \mathbf{P}\left\{\tau>t \mid X_{0}=x, Y_{0}=y\right\} \\
& \leq \max _{x, y \in \Omega} \frac{\mathbf{E}\left(\tau \mid X_{0}=x, Y_{0}=y\right)}{t}
\end{aligned}
$$

## Coupling

## Example



## Coupling

## Example



## Coupling

## Example



## Coupling

## Example



## Coupling

## Example



## Coupling

## Example

If we measure the clockwise distance between the two walkers, this coupling gives us a new Markov chain on $\{0,1, \ldots, n\}$ to study.


This gives us

$$
d(t) \leq \frac{n^{2}}{4 t} \rightarrow t_{\operatorname{mix}}(\epsilon) \leq \frac{n^{2}}{4 \epsilon}
$$

## 3-Regular Graphs

## Prism and Möbius ladder graphs



## 3-Regular Graphs

## Prism and Möbius ladder graphs



## 3-Regular Graphs

## GP(n,k)

Below is an example of $\operatorname{GP}(6,2)$.


Notice that if we imagined a cycle on the inside, the nodes which are the same color would be distance $\mathbf{2}$ away from eachother.

## 3-Regular Graphs

## Results

Using coupling, we were able to determine that for Möbius ladder graphs and prism graphs of size $n$, the mixing time for a (slightly modified) lazy random walk is bounded by

$$
t_{\text {mix }}(\epsilon) \leq \frac{3 n^{2}}{16 \epsilon}+\frac{6}{\epsilon}
$$

and for the generalized Petersen graph $\operatorname{GP}(n, k)$, the mixing time of the (slightly modified) lazy random walk is bounded by

$$
t_{\text {mix }}(\epsilon) \leq \frac{3|k|^{2}}{2 \epsilon}+\frac{3}{2 \epsilon}\left(\frac{n}{|k|}\right)^{2}+\frac{15}{\epsilon}
$$

where $|k|=n / \operatorname{gcd}(n, k)$.

## 3-Regular Graphs

## "Triangulating"

By "triangulating" a 3-regular graph, we mean replace each vertex with a complete graph of size 3 .


## 3-Regular Graphs

## "Triangulating"

By "triangulating" a 3-regular graph, we mean replace each vertex with a complete graph of size 3 .


## 3-Regular Graphs

## Example



## 3-Regular Graphs

## Example



## 3-Regular Graphs

## Results

We found that when you triangulate the Möbius ladder graphs and prism graphs of size $n$, your mixing time transforms into

$$
t_{\text {mix }}(\epsilon) \leq \frac{15 n^{2}}{16 \epsilon}+\frac{87}{5 \epsilon}
$$

For the generalized Petersen graph $\operatorname{GP}(n, k)$, it transforms into

$$
t_{\text {mix }}(\epsilon) \leq \frac{15|k|^{2}}{2 \epsilon}+\frac{15}{2 \epsilon}\left(\frac{n}{|k|}\right)^{2}+\frac{9}{\epsilon}\left(\frac{n}{|k|}\right)+\frac{9}{\epsilon}|k|+\frac{108}{\epsilon}
$$

where $|k|=n / \operatorname{gcd}(n, k)$.

## 3-Regular Graphs

## Remaining Questions

- Can we generalize this result to all vertex transitive 3-regular graphs?
- Can we extend it to all 3-regular graphs?
- Are the bounds we found above tight, or can we improve them?
- Does a similar result apply to lower bounds on these mixing times?


## References

David Aldous and Persi Diaconis, Shuffling cards and stopping times, The American Mathematical Monthly 93 (1986), no. 5, 333-348.
Richard Durrett and R Durrett, Essentials of stochastic processes, vol. 1, Springer, 1999.
围 David A. Levin, Yuval Peres, and Elizabeth L. Wilmer, Markov chains and mixing times, American Mathematical Society, 2006.

Sidney I Resnick, Adventures in stochastic processes, Springer Science \& Business Media, 2013.

## Acknowledgements

Thanks to Indiana University, Dr. Chris Connell, and the NSF for the REU and the opportunity to work on the project. Special thanks to Dr. Graham White.

